

Spatial evolutionary game simulator

S. Kolotev, A. Malyutin, E. Burovski, S. Krashakov and L. Shchur, *Dynamic fractals in spatial evolutionary games*, Physica A **499**, 142 (2018)

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In [1]:

```
import numpy as np
import matplotlib.pyplot as plt
import matplotlib as mpl
from matplotlib import animation

%matplotlib notebook
```

In [2]:

```
import sys
import cython

print("python ", sys.version)
print("numpy", np.__version__, ", matplotlib", mpl.__version__, ", and Cython",
      cython.__version__)

python 3.5.2 (default, Nov 17 2016, 17:05:23)
[GCC 5.4.0 20160609]
numpy 1.13.1 , matplotlib 2.0.2 , and Cython 0.27.3
```

Main update function:

In [3]:

```
def evolve2(field, b, num_steps=1):
    L = field.shape[0]
    current = np.zeros((L, L), dtype=int)
    scores = np.zeros((L, L), dtype=float)

    for step in range(num_steps):
        current = field.copy()
        scores = np.zeros((L, L), dtype=float)

        for x in range(L):
            for y in range(L):
                for i in range(-1, 2):
                    for j in range(-1, 2):
                        ix = (x + i) % L
                        jy = (y + j) % L
                        scores[x, y] += (1 - field[ix, jy])

                if field[x, y] == 1:
                    scores[x, y] *= b

        for x in range(L):
            for y in range(L):
                bestX = x
                bestY = y
                for i in range(-1, 2):
                    for j in range(-1, 2):
                        ix = (x + i) % L
                        jy = (y + j) % L
                        if (scores[bestX, bestY] < scores[ix, jy]):
                            bestX = ix
                            bestY = jy

                field[x, y] = current[bestX, bestY]
    return field
```

Run the simulation and animate

In [4]:

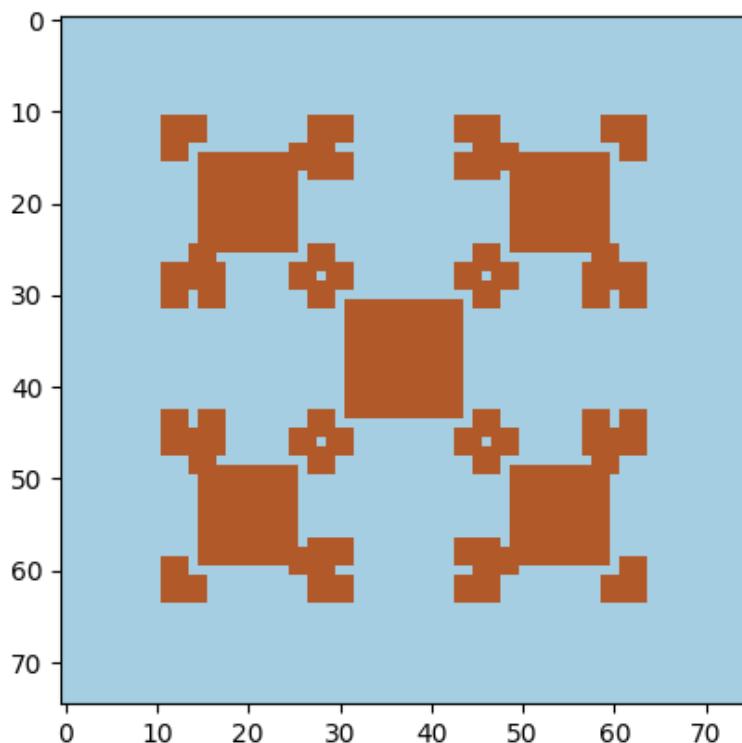
```
L = 75
field = np.zeros((L, L), dtype=int)
field[L//2, L//2] = 1

# draw the initial field
fig = plt.figure()
im = plt.imshow(field, animated=True, cmap=plt.get_cmap('Paired'))

# update function
def updatefig(*args):
    global field
    field = evolve2(field, 1.81, 1)
    im.set_array(field)
    return im,

# animate!
anim = animation.FuncAnimation(fig, updatefig, frames=200, interval=50, blit=True)

plt.show()
```



Timings

In [5]:

```
L = 44
field = np.zeros((L, L), dtype=int)
field[L//2, L//2] = 1

%timeit evolve2(field, 1.81, 10)
```

1 loop, best of 3: 345 ms per loop

Enter Cython

In class, we started with the original code and did the conversion iteratively, removing yellow lines from the annotated output. Below is only the final result.

In [6]:

```
%load_ext cython
```

In [7]:

```
%%cython -a

import numpy as np

import cython

@cython.cdivision(True)
@cython.boundscheck(False)
def evolve2_1(long[:, ::1] field, double b, int num_steps=1):

    cdef int x, y, L, i, j, ix, jy, step

    L = field.shape[0]
    cdef double[:, ::1] scores = np.zeros((L, L), dtype=float)

    cdef double[:, ::1] _zeros = np.zeros((L, L), dtype=float)
    cdef long[:, ::1] current = field.copy()

    for step in range(num_steps):
        current = field.copy()
        scores[...] = _zeros

        for x in range(L):
            for y in range(L):
                for i in range(-1, 2):
                    for j in range(-1, 2):
                        ix = (x + i) % L
                        jy = (y + j) % L
                        scores[x, y] += (1 - field[ix, jy])

                if field[x, y] == 1:
                    scores[x, y] *= b

        for x in range(L):
            for y in range(L):
                bestX = x
                bestY = y
                for i in range(-1, 2):
                    for j in range(-1, 2):
                        ix = (x + i) % L
                        jy = (y + j) % L
                        if (scores[bestX, bestY] < scores[ix, jy]):
                            bestX = ix
                            bestY = jy

                field[x, y] = current[bestX, bestY]

    return field
```

Out[7]:

Generated by Cython 0.25.2

Yellow lines hint at Python interaction.

Click on a line that starts with a "+" to see the C code that Cython generated for it.

```
+01:
+02: import numpy as np
03:
04: import cython
05:
06: @cython.cdivision(True)
07: @cython.boundscheck(False)
+08: def evolve2_1(long[:, ::1] field, double b, int num_steps=1):
09:
10:     cdef int x, y, L, i, j, ix, jy, step
11:
12:     L = field.shape[0]
13:     cdef double[:, ::1] scores = np.zeros((L, L), dtype=float)
14:
15:     cdef double[:, ::1] _zeros = np.zeros((L, L), dtype=float)
16:     cdef long[:, ::1] current = field.copy()
17:
18:     for step in range(num_steps):
19:         current = field.copy()
20:         scores[...] = _zeros
21:
22:         for x in range(L):
23:             for y in range(L):
24:                 for i in range(-1, 2):
25:                     for j in range(-1, 2):
26:                         ix = (x + i) % L
27:                         jy = (y + j) % L
28:                         scores[x, y] += (1 - field[ix, jy])
29:
30:                         if field[x, y] == 1:
31:                             scores[x, y] *= b
32:
33:         for x in range(L):
34:             for y in range(L):
35:                 bestX = x
36:                 bestY = y
37:                 for i in range(-1, 2):
38:                     for j in range(-1, 2):
39:                         ix = (x + i) % L
40:                         jy = (y + j) % L
41:                         if (scores[bestX, bestY] < scores[ix, jy]):
42:                             bestX = ix
43:                             bestY = jy
44:
```

```
+45:             field[x, y] = current[bestX, bestY]
+46:     return field
```

In [10]:

```
L = 44
field = np.zeros((L, L), dtype=int)
field[L//2, L//2] = 1

%timeit evolve2_1(field, 1.81, 10)
```

```
100 loops, best of 3: 1.98 ms per loop
```

In [11]:

```
345 / 1.98
```

Out[11]:

```
174.24242424242425
```

The recommended code structure is to have a python-facing **def** function which takes care of the input and output, allocated memory etc, and delegates all heavy lifting to an internal **cdef** function.


```
cdef int x, y, L, i, j, ix, jy, step
L = field.shape[0]

for step in range(num_steps):
    current[...] = field
    scores[...] = _zeros

    for x in range(L):
        for y in range(L):
            for i in range(-1, 2):
                for j in range(-1, 2):
                    ix = (x + i) % L
                    jy = (y + j) % L
                    scores[x, y] += (1 - field[ix, jy])

                    if field[x, y] == 1:
                        scores[x, y] *= b

    for x in range(L):
        for y in range(L):
            bestX = x
            bestY = y
            for i in range(-1, 2):
                for j in range(-1, 2):
                    ix = (x + i) % L
                    jy = (y + j) % L
                    if (scores[bestX, bestY] < scores[ix, jy]):
                        bestX = ix
                        bestY = jy

    field[x, y] = current[bestX, bestY]
```

Out[12]:

Generated by Cython 0.25.2

Yellow lines hint at Python interaction.
Click on a line that starts with a "+" to see the C code that Cython generated for it.

```
+01: 01:
+02: import numpy as np
+03: import cython
+04:
+05: def evolve2_2(field, b, num_steps=1):
+06:     # validate input here
+07:     field = np.atleast_2d(field)
+08:     # XXX check that field is integer dtype etc
+09:
+10:    # allocate memory here
+11:    L = field.shape[0]
+12:    scores = np.zeros((L, L), dtype=float)
+13:    current = field.copy()
+14:    _zeros = np.zeros((L, L), dtype=float)
+15:
+16:    cdef:
+17:        int _num_steps = num_steps
+18:        double _b = b
+19:
+20:        # do the work (`field` array is updated in-place)
+21:        _evolve2_2_impl(field, _b, _num_steps, scores, _zeros, current)
+22:
+23:        # convert memoryviews to numpy arrays
+24:    return np.asarray(field)
+25:
+26:
+27: @cython.cdivision(True)
+28: @cython.boundscheck(False)
+29: cdef void _evolve2_2_impl(long[:, ::1] field, double b, int num_steps,
+30:                             double[:, ::1] scores,
+31:                             double[:, ::1] _zeros,
+32:                             long[:, ::1] current) nogil:
+33:     cdef int x, y, L, i, j, ix, jy, step
+34:
+35:     L = field.shape[0]
+36:
+37:     for step in range(num_steps):
+38:         current[...] = field
+39:         scores[...] = _zeros
+40:
+41:         for x in range(L):
+42:             for y in range(L):
```

```

+43:             for i in range(-1, 2):
+44:                 for j in range(-1, 2):
+45:                     ix = (x + i) % L
+46:                     jy = (y + j) % L
+47:                     scores[x, y] += (1 - field[ix, jy])
48:
+49:             if field[x, y] == 1:
+50:                 scores[x, y] *= b
51:
+52:         for x in range(L):
+53:             for y in range(L):
+54:                 bestX = x
+55:                 bestY = y
+56:                 for i in range(-1, 2):
+57:                     for j in range(-1, 2):
+58:                         ix = (x + i) % L
+59:                         jy = (y + j) % L
+60:                         if (scores[bestX, bestY] < scores[ix,
jy]):
+61:                             bestX = ix
+62:                             bestY = jy
63:
+64:         field[x, y] = current[bestX, bestY]

```

In [13]:

```

L = 44
field = np.zeros((L, L), dtype=int)
field[L//2, L//2] = 1

%timeit evolve2_2(field, 1.81, 10)

```

1000 loops, best of 3: 1.8 ms per loop

**Now, for something completely different:
numba just-in-time compilation**

In [14]:

```
import numba
```

In [15]:

```
def evolve3(field, b, num_steps=1):
    L = field.shape[0]
    _zeros = np.zeros((L, L), dtype=float)
    _int_zeros = np.zeros((L, L), dtype=int)
    current = _int_zeros.copy()
    scores = _zeros.copy()
    evolve3_impl(field, b, num_steps, _zeros, _int_zeros)
    return field

# Note a single decorator: @jit

@numba.jit(nopython=True)
def evolve3_impl(field, b, num_steps, _zeros, _int_zeros):
    L = field.shape[0]
    current = _int_zeros.copy()

    for step in range(num_steps):
        current = field.copy()
        scores = _zeros.copy()

        for x in range(L):
            for y in range(L):
                for i in range(-1, 2):
                    for j in range(-1, 2):
                        ix = (x + i) % L
                        jy = (y + j) % L
                        scores[x, y] += (1 - field[ix, jy])

                if field[x, y] == 1:
                    scores[x, y] *= b

        for x in range(L):
            for y in range(L):
                bestX = x
                bestY = y
                for i in range(-1, 2):
                    for j in range(-1, 2):
                        ix = (x + i) % L
                        jy = (y + j) % L
                        if (scores[bestX, bestY] < scores[ix, jy]):
                            bestX = ix
                            bestY = jy

                field[x, y] = current[bestX, bestY]
    return field
```

In [16]:

```
L = 44
field = np.zeros((L, L), dtype=int)
field[L//2, L//2] = 1

%timeit evolve3(field, 1.81, 10)
```

The slowest run took 252.75 times longer than the fastest. This could mean that an intermediate result is being cached.
1 loop, best of 3: 2.14 ms per loop

In []: